

# Linear models with an arbitrary set of perturbations. Spectral equation $S_5$

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Assume that a linear regression model

$$\vec{y} = X\vec{c} + \vec{\varepsilon}$$

is given, where  $\vec{c}$  is an unknown  $m$ -dimensional vector,  $\vec{y}$  is an  $n$ -dimensional vector of observations,  $X = (x_{ij}), j = 1, \dots, m, i = 1, \dots, n; n \geq m$  is a matrix, and  $\vec{\varepsilon}$  is an  $n$ -dimensional vector of unobservable perturbations.

Let the vectors  $\vec{c}$  and  $\vec{\varepsilon}$  belong to the measurable bounded domains  $C \subset K_m$  and  $E \subset K_n$ , respectively. By means of a linear transformation of the vector  $\vec{y} : T_{m \times n} \vec{y} + \vec{t}_m$  we find a matrix  $\hat{T}_{m \times n}$  and vector  $\hat{\vec{t}}$  which minimize the loss function

$$\varphi(T, \vec{t}) := \sup_{\vec{\varepsilon} \in E, \vec{c} \in C} f \left\{ (T\vec{y} - \vec{t} - \vec{c})^T V (T\vec{y} - \vec{t} - \vec{c}) \right\},$$

where  $V_{m \times m}$  is a nonnegative definite matrix and  $f$  is a certain differentiable function which satisfies conditions of Theorem 5.1. The vector  $\hat{\vec{c}} = \hat{T}\vec{y} + \hat{\vec{t}}$  is called the  $S_5$ -estimator (or minimax estimator) of the vector  $\vec{c}$ .

Using the main spectral equation as in Section 5 we have that

$$\begin{aligned} & \inf_{T \in L_{m \times n}, \vec{t} \in K_m} \sup_{\vec{\varepsilon} \in E, \vec{c} \in C} f \left\{ (T\vec{y} - \vec{t} - \vec{c})^T V (T\vec{y} - \vec{t} - \vec{c}) \right\} \\ &= \inf_{T \in L_{m \times n}, \vec{t} \in K_m} \lim_{N \rightarrow \infty} \lambda_1 [A_N(T, \vec{t})], \end{aligned}$$

where

$$A_N(T, \vec{t}) = (a_{ij})_{i,j=1}^N,$$

$$\begin{aligned} a_{ij} &= \int_{\vec{\varepsilon} \in E, \vec{c} \in C} \theta_i(\vec{\varepsilon}, \vec{c}) \theta_j(\vec{\varepsilon}, \vec{c}) f \left\{ [(TX - I)\vec{c} - T\vec{\varepsilon} - \vec{t}]^T V [(TX - I)\vec{c} - T\vec{\varepsilon} - \vec{t}] \right\} \\ &\quad \times \prod_{\substack{p=1, \dots, n \\ l=1, \dots, m}} d\varepsilon_p d c_l, \end{aligned}$$

$\theta_j(\vec{\varepsilon}, \vec{c})$  is an arbitrary orthonormal system of functions in the domain  $C \times E$ .

Therefore, we can change our problem: find matrix  $T_N^*$  and vector  $\vec{t}_N^*$  which minimize the expression

$$\inf_{T \in L_{m \times n}, \vec{t} \in K_m} \lambda_1 [A_N (T, \vec{t})] = \lambda_1 [A_N (T_N^*, \vec{t}_N^*)].$$

Using the proof of Theorem 6.2 we obtain that the matrix  $T_N^* \in L_{m \times n}$  and the vector  $\vec{t}_N^* \in K_m$  satisfy the system of equations  $S_5$ .

$$\begin{aligned} & \sum_{k=1}^s \vec{v}_k^T \left\{ \int_{\vec{\varepsilon} \in E, \vec{c} \in C} \theta_i(\vec{\varepsilon}, \vec{c}) \theta_j(\vec{\varepsilon}, \vec{c}) V((T_N^* X - I) \vec{c} - T_N^* \vec{\varepsilon} - \vec{t}_N^*) \right. \\ & \quad \times (\vec{c}^T X^T - \vec{\varepsilon}^T) \frac{\partial f}{\partial u} \left\{ [(T_N^* X - I) \vec{c} - T_N^* \vec{\varepsilon} - \vec{t}_N^*]^T \right. \\ & \quad \left. \left. V[(T_N^* X - I) \vec{c} - T_N^* \vec{\varepsilon} - \vec{t}_N^*] \right\} \prod_{p,l} d\varepsilon_p dc_l; \right. \\ & \left. \sum_{k=1}^s \vec{v}_k^T \left\{ \int_{\vec{\varepsilon} \in E, \vec{c} \in C} \theta_i(\vec{\varepsilon}, \vec{c}) \theta_j(\vec{\varepsilon}, \vec{c}) V((T_N^* X - I) \vec{c} - T_N^* \vec{\varepsilon} - \vec{t}_N^*) \right\} \right\}_{i,j=1}^N \\ & \quad \times \frac{\partial f}{\partial u} \left\{ [(T_N^* X - I) \vec{c} - T_N^* \vec{\varepsilon} - \vec{t}_N^*]^T V[(T_N^* X - I) \vec{c} - T_N^* \vec{\varepsilon} - \vec{t}_N^*] \right\} \\ & \quad \times \prod_{p,l} d\varepsilon_p dc_l \vec{v}_k p_k = 0, \end{aligned}$$

where  $\vec{v}_k$ ,  $k = 1, \dots, s$  are the eigenvectors corresponding to the maximal  $j$ -multiple eigenvalue  $\lambda_1(A_N)$  of the matrix  $A_N$ ,

$$\sum_{k=1}^s p_k = 1; \quad p_k > 0, \quad k = 1, \dots, s.$$

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